## 空なる証明の道

Ku naru shoh-mei no michi

The way of the empty proof L'art de la preuve vide

If you have the right definition you have a simpler proof.

If you have the right data structures, you have a simpler algorithm.

If you have the right.....

## **Power of Elimination**

## 除去の力

#### Tarski's Meta-theorem

To any formula  $Φ(X_1, X_2,....,X_m)$  in the vocabulary  $\{0,1,+,.,=,<\}$  one can effectively associate two objects:

- (i) a quantifier free formula  $\theta(X_1,....,X_m)$  in the same vocabulary and
- (ii) a proof of the equivalence  $\Phi \leftarrow \rightarrow \theta$  that uses the axioms for real closed fields.

$$\exists x \ ax^2 + b + c = 0$$

If and only if  $b^2 - 4ac > 0$ 

## Resolution: Tarski's Meta-theorem for Logic

Elimination not restricted to algebra and geometry

$$362x - 9y \le 55$$
  
 $2(63x + 2y \le -2)$   
 $0x - 7y \le 13$ 

Used in automated theorem proving (algebra, geometry & logic)

But...

However...

Can be used in special cases to prove theorems by hand

The elimination of the proof is an ideal seldom reached

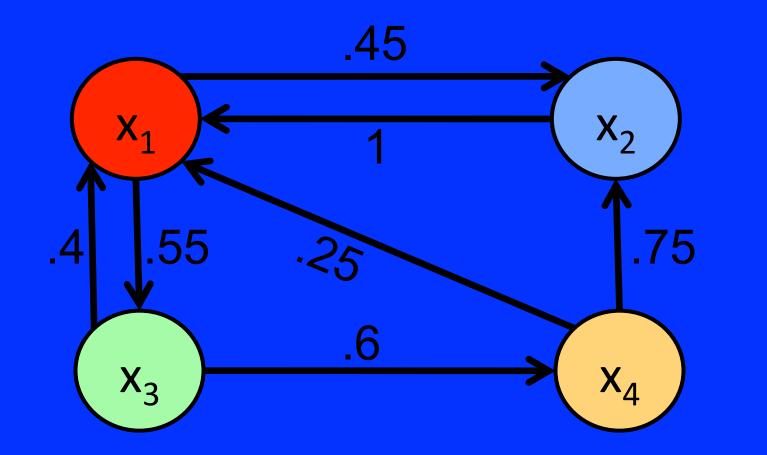
Elimination gives us the heart of the proof

## Markov's Ergodic Theorem (1906)

Any irreducible, finite, aperiodic Markov Chain has all states Ergodic (reachable at any time in the future) and has a unique stationary distribution, which is a probability vector.

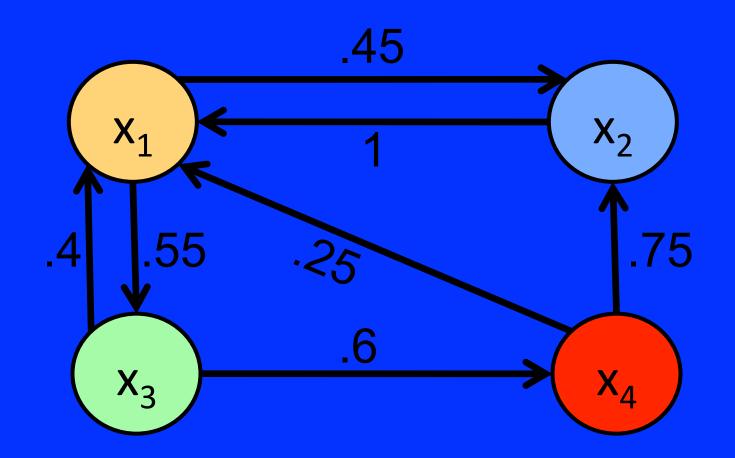
#### **Probabilities**

after 15 steps	30 steps	100 steps	500 steps	1000 steps
X1 = .33	X1 = .33	X1 = .37	X1 = .38	X1 = .38
X2 = .26	X2 = .26	X2 = .29	X2 = .28	X2 = .28
X3 = .26	X3 = .23	X3 = .21	X3 = .21	X3 = .21
X4 = .13	X4 = .16	X4 = .13	X4 = .13	X4 = .13



#### **Probabilities**

after 15 steps	30 steps	100 steps	500 steps	1000 steps
X1 = .46	X1 = .36	X1 = .38	X1 = .38	X1 = .38
X2 = .20	X2 = .26	X2 = .28	X2 = .28	X2 = .28
X3 = .26	X3 = .23	X3 = .21	X3 = .21	X3 = .21
X4 = .06	X4 = .13	X4 = .13	X4 = .13	X4 = .13



$$p_{11}x_1 + p_{21}x_2 + p_{31}x_3 = x_1$$

$$p_{12}x_1 + p_{22}x_2 + p_{32}x_3 = x_2$$

$$p_{13}x_1 + p_{23}x_2 + p_{33}x_3 = x_3$$

$$\sum x_i = 1$$

$$x_i \ge 0$$

You can view the problem in three different ways:

- Principal eigenvector problem
- Classical Linear Programming problem
- Elimination problem

## Difficulties as an Eigenvector Problem

- Notion of convergence
- Deal with complex numbers
- Uniqueness of solution

 Need to use theorems: Perron-Frobenius, Chapman, Kolmogoroff, Cauchy... and/or restrictive hypotheses....

## Symbolic Gaussian Elimination

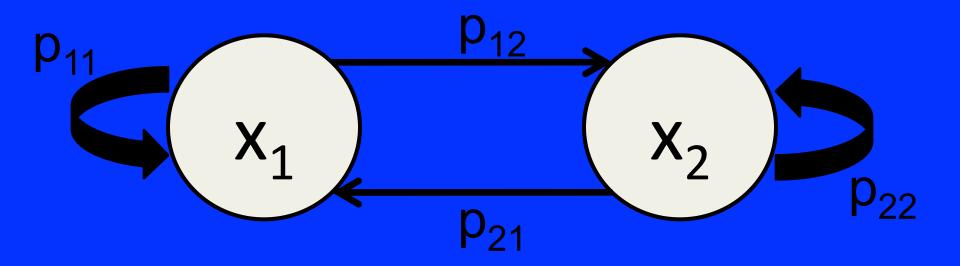
#### System of two variables:

$$p_{11}x_1 + p_{21}x_2 = x_1$$
  
 $p_{12}x_1 + p_{22}x_2 = x_2$   
 $\sum x_i = 1$ 

#### With Maple we find:

$$x_1 = p_{21}/(p_{21} + p_{12})$$
  
 $x_2 = p_{12}/(p_{21} + p_{12})$ 

$$x_1 = p_{21}/(p_{21} + p_{12})$$
  
 $x_2 = p_{12}/(p_{21} + p_{12})$ 



## Symbolic Gaussian Elimination

#### Three variables:

$$p_{11}x_1 + p_{21}x_2 + p_{31}x_3 = x_1$$

$$p_{12}x_1 + p_{22}x_2 + p_{32}x_3 = x_2$$

$$p_{13}x_1 + p_{23}x_2 + p_{33}x_3 = x_3$$

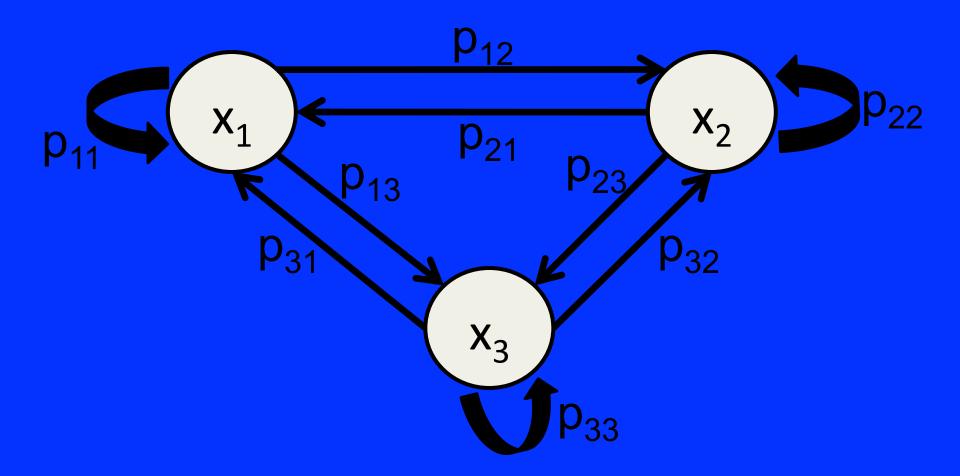
$$\sum x_i = 1$$

#### With Maple we find:

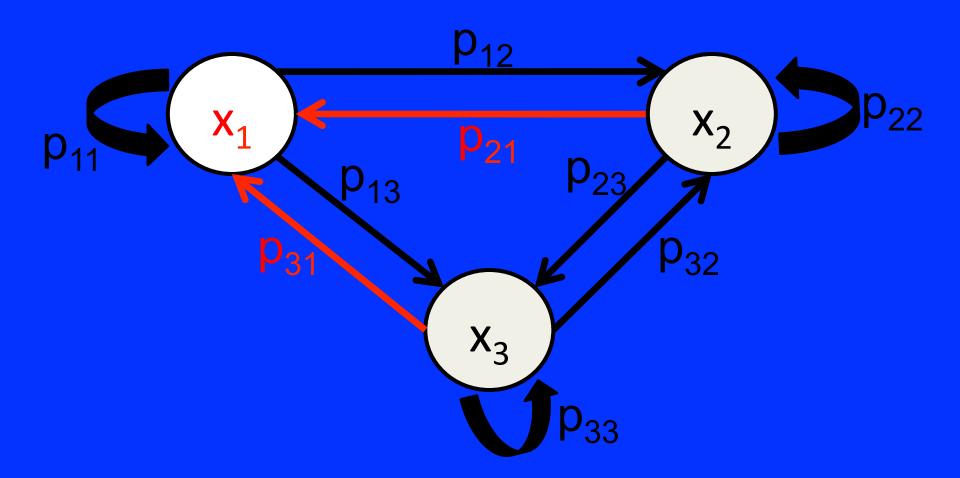
$$x_1 = (p_{31}p_{21} + p_{31}p_{23} + p_{32}p_{21}) / \Sigma$$
  
 $x_2 = (p_{13}p_{32} + p_{12}p_{31} + p_{12}p_{32}) / \Sigma$   
 $x_3 = (p_{13}p_{21} + p_{12}p_{23} + p_{13}p_{23}) / \Sigma$ 

$$\Sigma = (p_{31}p_{21} + p_{31}p_{23} + p_{32}p_{21} + p_{13}p_{32} + p_{12}p_{31} + p_{12}p_{32} + p_{13}p_{21} + p_{12}p_{23} + p_{13}p_{23})$$

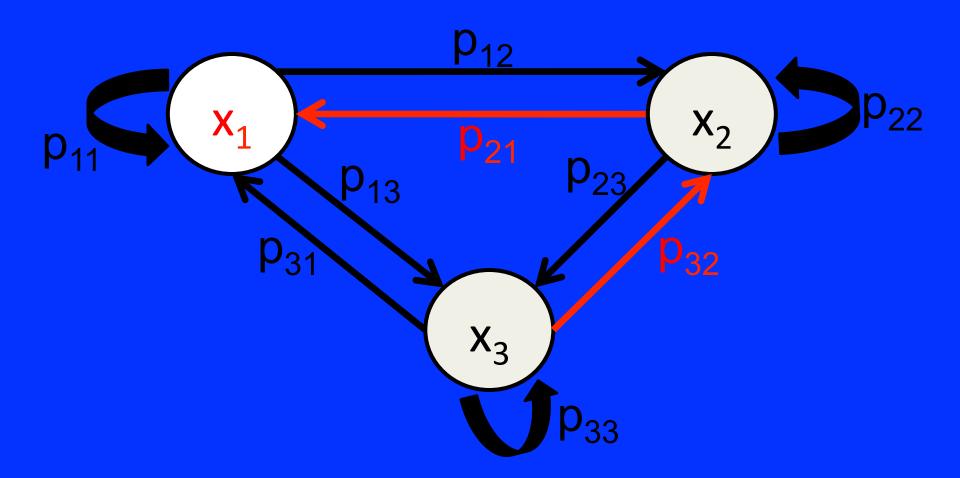
$$x_1 = (p_{31}p_{21} + p_{23}p_{31} + p_{32}p_{21}) / \Sigma$$
  
 $x_2 = (p_{13}p_{32} + p_{31}p_{12} + p_{12}p_{32}) / \Sigma$   
 $x_3 = (p_{21}p_{13} + p_{12}p_{23} + p_{13}p_{23}) / \Sigma$ 



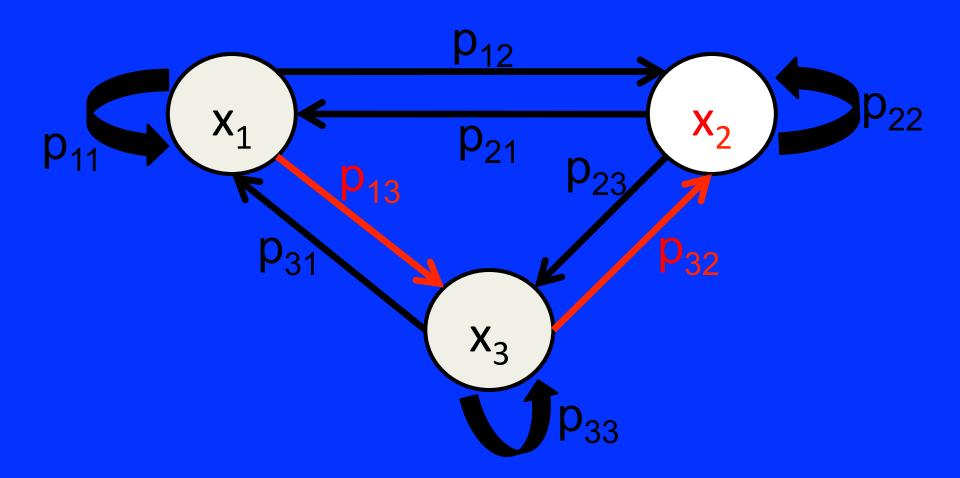
$$x_1 = (p_{31}p_{21} + p_{23}p_{31} + p_{32}p_{21}) / \Sigma$$
  
 $x_2 = (p_{13}p_{32} + p_{31}p_{12} + p_{12}p_{32}) / \Sigma$   
 $x_3 = (p_{21}p_{13} + p_{12}p_{23} + p_{13}p_{23}) / \Sigma$ 



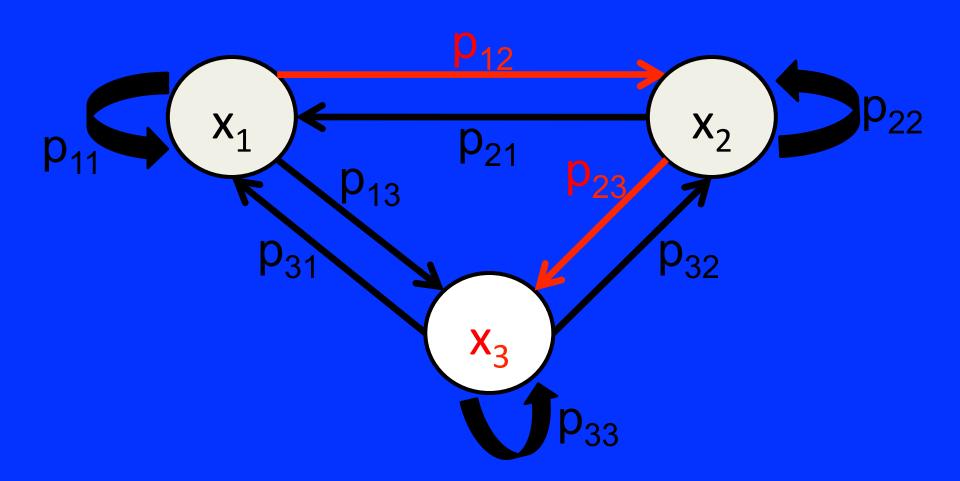
$$x_1 = (p_{31}p_{21} + p_{23}p_{31} + p_{32}p_{21}) / \Sigma$$
  
 $x_2 = (p_{13}p_{32} + p_{31}p_{12} + p_{12}p_{32}) / \Sigma$   
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$$x_1 = (p_{31}p_{21} + p_{23}p_{31} + p_{32}p_{21}) / \Sigma$$
  
 $x_2 = (p_{13}p_{32} + p_{31}p_{12} + p_{12}p_{32}) / \Sigma$   
 $x_3 = (p_{21}p_{13} + p_{12}p_{23} + p_{13}p_{23}) / \Sigma$ 



## Do you see the LIGHT?

James Brown (The Blues Brothers)

## Symbolic Gaussian Elimination

System of four variables:

$$p_{21}x_{2} + p_{31}x_{3} + p_{41}x_{4} = x_{1}$$

$$p_{12}x_{1} + p_{42}x_{4} = x_{2}$$

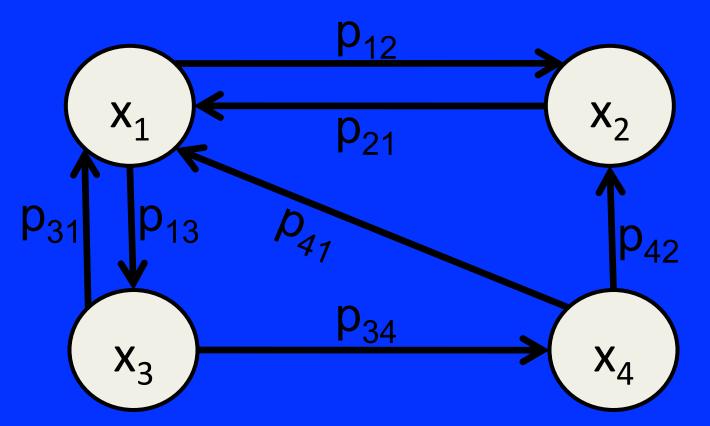
$$p_{13}x_{1} = x_{3}$$

$$p_{34}x_{3} = x_{4}$$

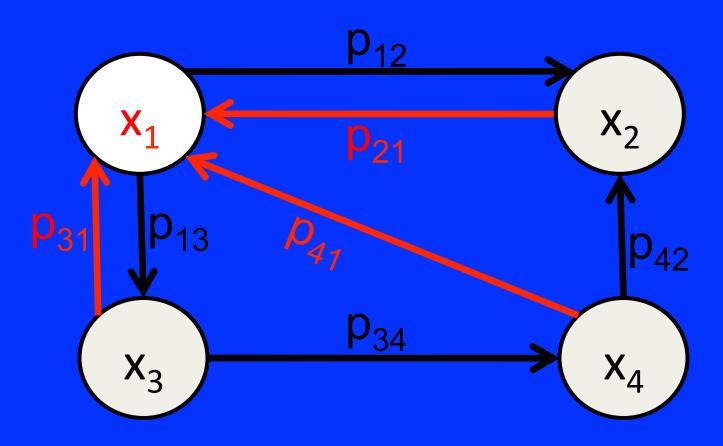
$$\sum x_{i} = 1$$

#### With Maple we find:

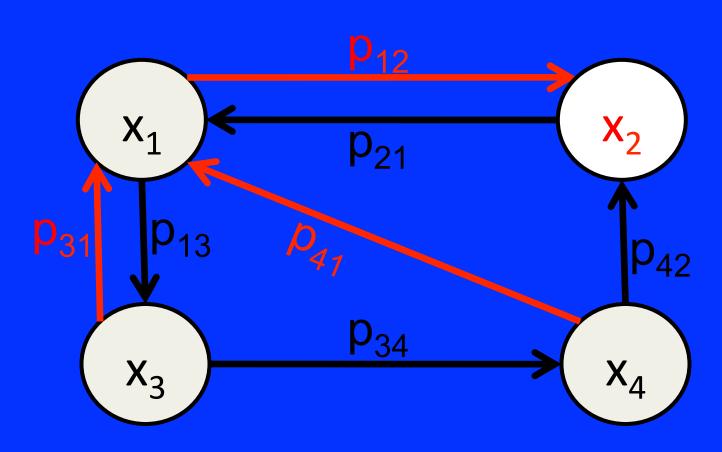
$$\begin{aligned} x_1 &= p_{21}p_{34}p_{41} + p_{34}p_{42}p_{21} + p_{21}p_{31}p_{41} + p_{31}p_{42}p_{21} / \Sigma \\ x_2 &= p_{31}p_{41}p_{12} + p_{31}p_{42}p_{12} + p_{34}p_{41}p_{12} + p_{34}p_{42}p_{12} + p_{13}p_{34}p_{42} / \Sigma \\ x_3 &= p_{41}p_{21}p_{13} + p_{42}p_{21}p_{13} / \Sigma \\ x_4 &= p_{21}p_{13}p_{34} / \Sigma \end{aligned}$$



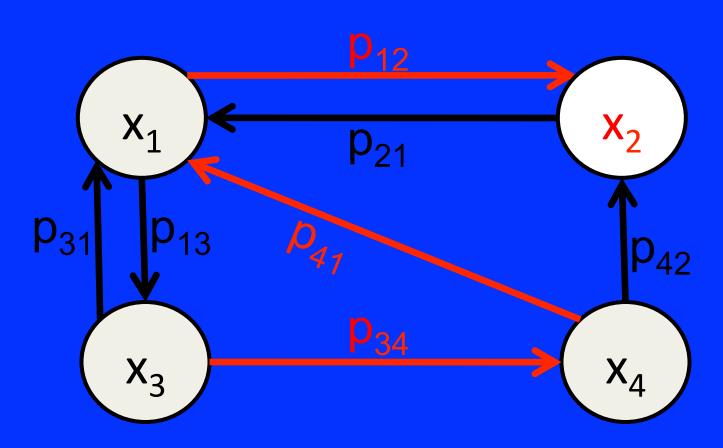
$$\begin{array}{l} x_1 = p_{21}p_{34}p_{41} + p_{34}p_{42}p_{21} + p_{21}p_{31}p_{41} + p_{31}p_{42}p_{21} / \Sigma \\ x_2 = p_{31}p_{41}p_{12} + p_{31}p_{42}p_{12} + p_{34}p_{41}p_{12} + p_{34}p_{42}p_{12} + p_{13}p_{34}p_{42} / \Sigma \\ x_3 = p_{41}p_{21}p_{13} + p_{42}p_{21}p_{13} / \Sigma \\ x_4 = p_{21}p_{13}p_{34} / \Sigma \end{array}$$



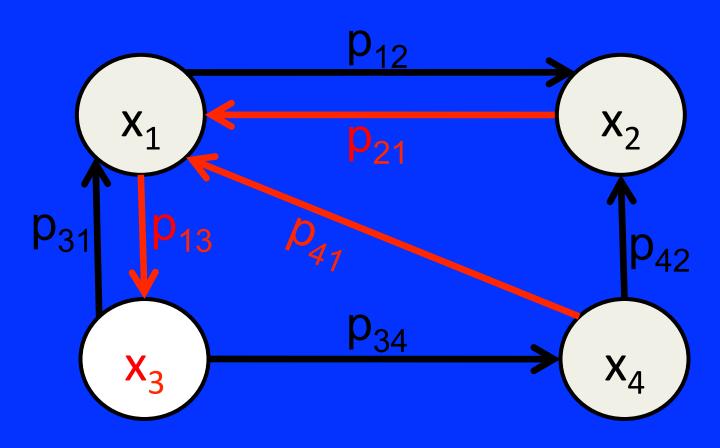
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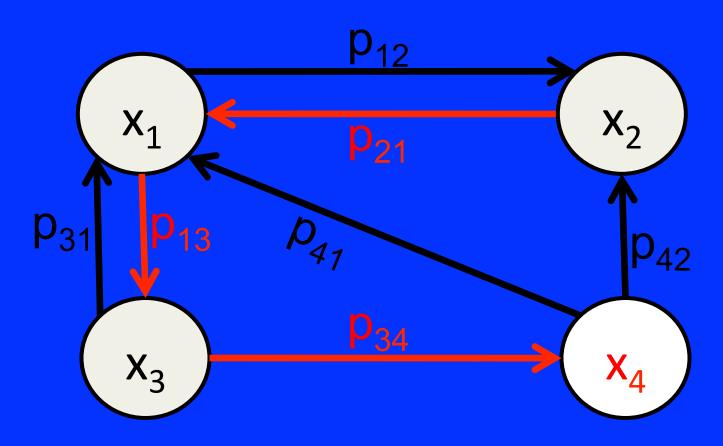
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## **Ergodic Theorem Revisited**

If there exists a reverse spanning tree in a graph of the Markov chain associated to a stochastic system, then:

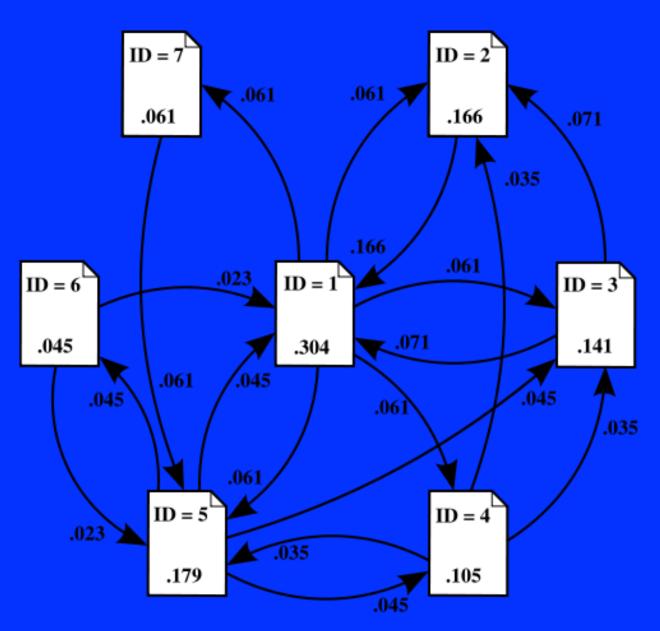
(a) the stochastic system admits the following probability vector as a solution:

$$\left\{x_i = \frac{W(i)}{\sum_j W(j)}\right\} i = 1, n$$

- (b) the solution is unique.
- (c) the conditions  $\{x_i \ge 0\}_{i=1,n}$  are redundant and the solution can be computed by Gaussian elimination.

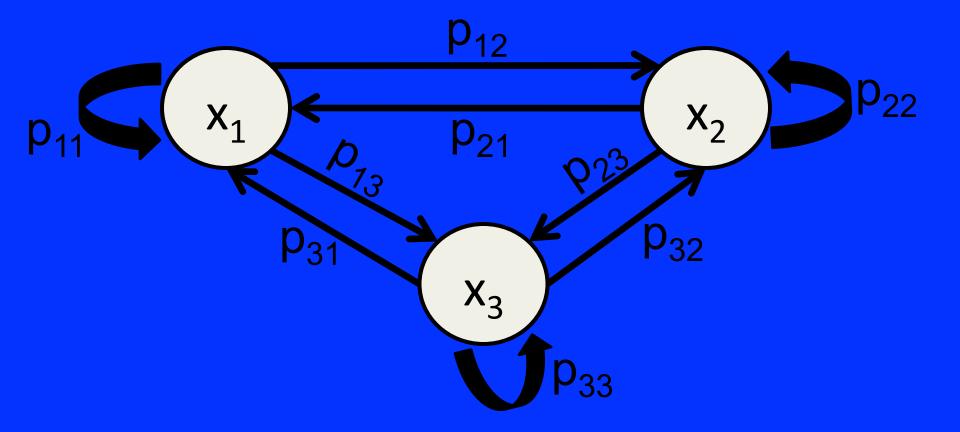
#### Internet Sites

- Kleinberg
- Google
- SALSA
- In degree heuristic



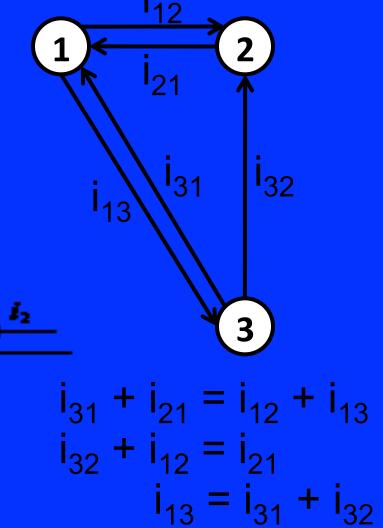
### Markov Chain as a Conservation System

$$p_{11}x_1 + p_{21}x_2 + p_{31}x_3 = x_1(p_{11} + p_{12} + p_{13})$$
  
 $p_{12}x_1 + p_{22}x_2 + p_{32}x_3 = x_2(p_{21} + p_{22} + p_{23})$   
 $p_{13}x_1 + p_{23}x_2 + p_{33}x_3 = x_3(p_{31} + p_{32} + p_{33})$ 



## Kirchoff's Current Law

The sum of currents
 flowing towards a node is
 equal to the sum of
 currents flowing away
 from the node.



$$i_3 + i_2 = i_1 + i_4$$

# Kirchoff's Matrix Tree Theorem (1847)

For an n-vertex digraph, define an n x n matrix A such that A[i,j] = 1 if there is an edge from i to j, for all  $i \neq j$ , and the diagonal entries are such that the row sums are 0.

Let A(k) be the matrix obtained from A by deleting row k and column k. Then the absolute value of the determinant of A(k) is the number of spanning trees rooted at k (edges directed towards vertex k)

## Two theorems for the price of one!!

#### **Differences**

- Kirchoff theorem perform n gaussian eliminations
- Revised version only two gaussian

#### Minimax Theorem

- Fundamental Theorem in Game Theory
- Von Neumann & Kuhn

 Minimax Theorem brings certainty into the world of probabilistic game theory.

Applications in Computer Science, Economics
 & Business, Biology, etc.

#### Minimax Theorem

$$max(x + 2y)$$

$$11z \le 30/11$$

$$-233 \le 2$$

$$0 \le z \le 1$$

max value z can take is min value of the right hand side

min value z can take is max value of the left hand side

## **Duality Theorem**

If the primal problem has an optimal solution,

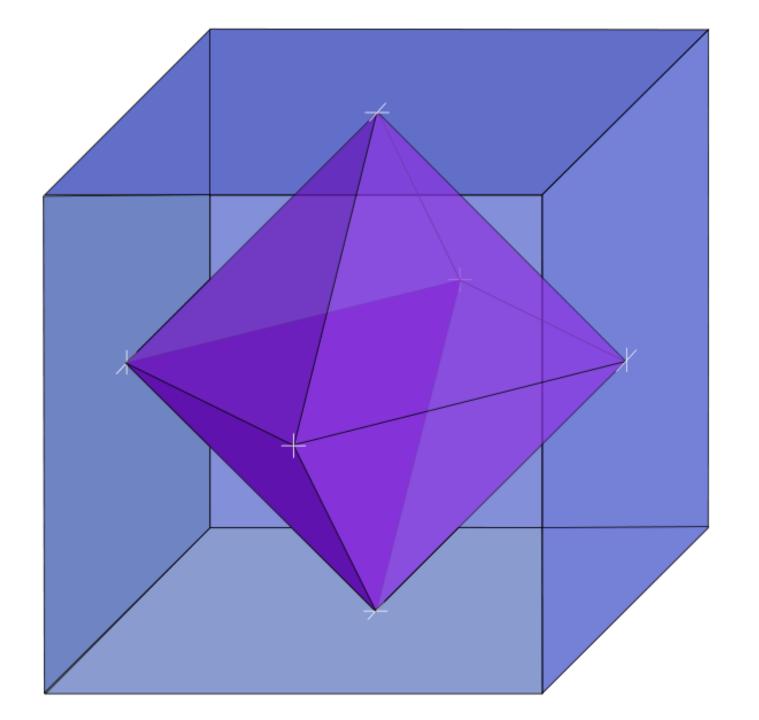
$$x^* = (x_1^*, x_2^*, \dots, x_n^*)$$

then the dual also has an optimal solution,

$$y^* = (y_1^*, y_2^*, \dots, y_m^*)$$

and

$$\max \sum_{j} c_{j} x_{j} = \min \sum_{i} b_{i} y_{i}$$



# 幾何学

Γεωμετρία

Géométrie

Geometry

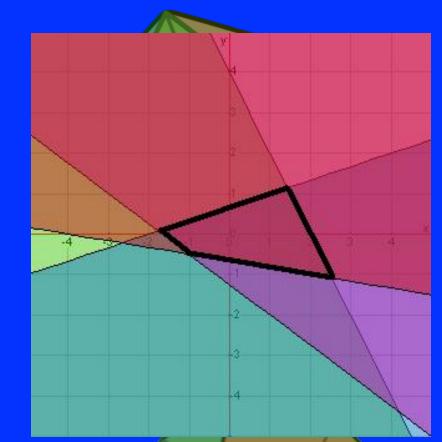
# Κανένας δεν εισάγει εκτός αν ξέρει τη γεωμετρία Πλάτων

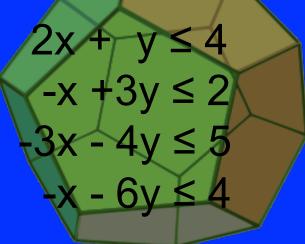
Nobody enters unless he knows Geometry *Plato*  κανένας δεν παίρνει από εδώ εκτός αν ξέρει τη γεωμετρία Jean-Louis L.

#### 彼が幾何学を知っていなければだれも出ない

Personne ne sort s' il ne connait la Géométrie

Nobody gets out unless he knows Geometry A polyhedron is defined as the intersection of a finite number of linear halfspaces.





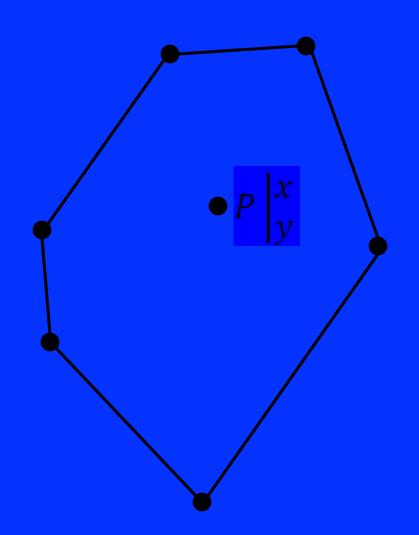
A polytope Q is defined as a convex hull of a finite collection of points.

$$x = \sum \lambda_i x_i$$

$$y = \sum \lambda_i y_i$$

$$\sum \lambda_i = 1$$

$$\lambda_i \ge 0$$



# Minkowski(1896)-Steinitz(1916)-Farkas(1906)-Weyl(1935) Theorem

Q is a polytope if and only if it is a bounded polyhedron.

Extension by Charnes & Cooper (1958)

"This classical result is an outstanding example of a fact which is completely obvious to geometric intuition, but wields important algebraic content and is not trivial to prove."

### R.T. Rockafeller

A polytope Q is defined as a convex hull of a finite collection of points.

$$\lambda_{3} = \lambda_{2} - \lambda_{2} - \lambda_{2} - \lambda_{2}$$

$$\lambda_{1} + 2 \lambda_{2} + 2 \lambda_{3} \ge 0$$

$$\lambda_{1} + 2 \lambda_{2} + 2 \lambda_{3} \ge 0$$

$$\lambda_{1} + 2 \lambda_{2} + 2 \lambda_{3} \ge 0$$

$$\lambda_{1} + 2 \lambda_{2} + 2 \lambda_{3} \ge 0$$

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$$\lambda_{1} + 2 \lambda_{2} + 2 \lambda_{3} \ge 0$$

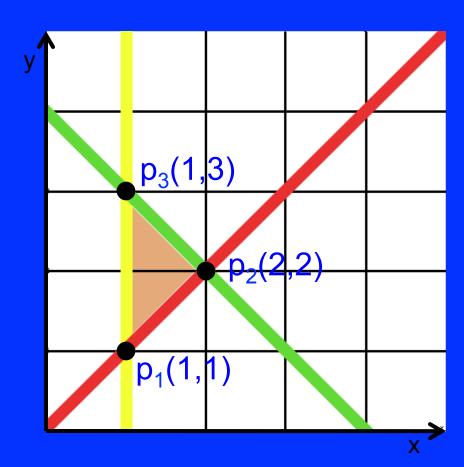
$$\lambda_{1} + 2 \lambda_{2} + 2 \lambda_{3} \ge 0$$

$$\lambda_{1} + 2 \lambda_{2} + 2 \lambda_{3} \ge 0$$

$$\lambda_{2} + \lambda_{3} \ge 0$$

$$\lambda_{3} \ge 0$$

$$\lambda_{3} \ge 0$$



A polyhedron is defined as the intersection of a finite number of linear halfspaces.

#### References

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