

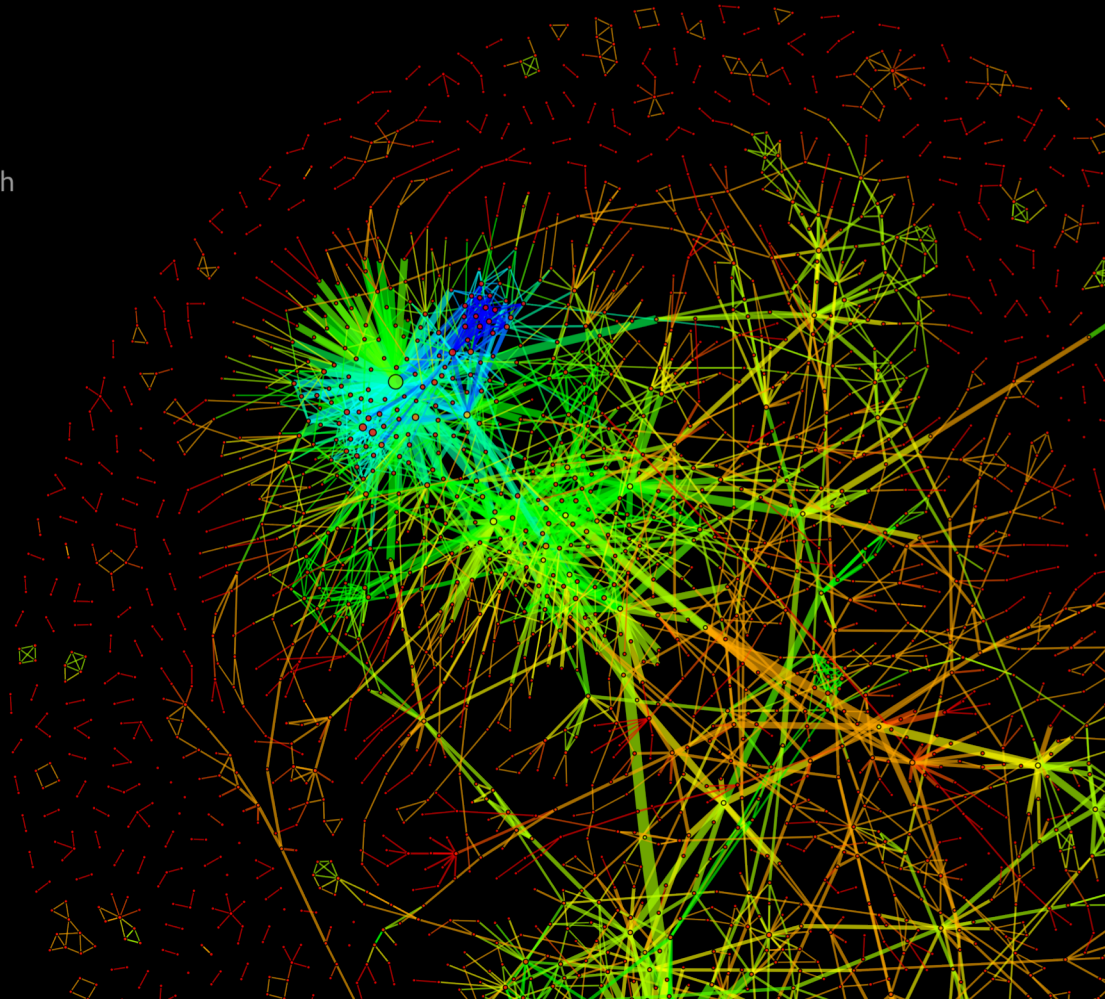
Relational Similarity Machines (RSM): A Similarity-based Learning Framework for Graphs

Ryan A. Rossi
Adobe Research



Joint work with:

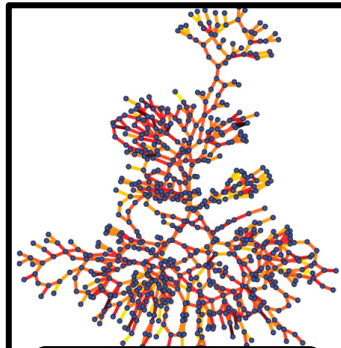
Rong Zhou (Google)
Nesreen K. Ahmed (Intel Labs)
Hoda Eldardiry (Xerox PARC)



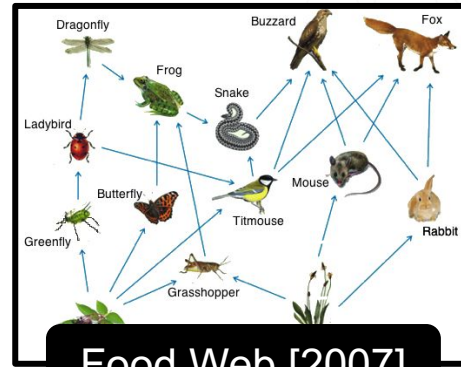
Graphs – rich and powerful data representation



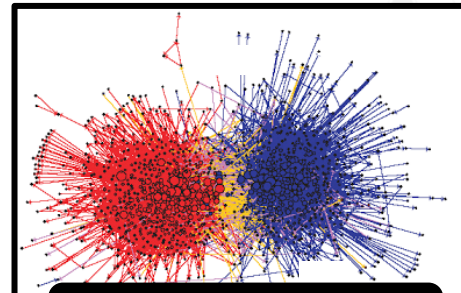
Social network



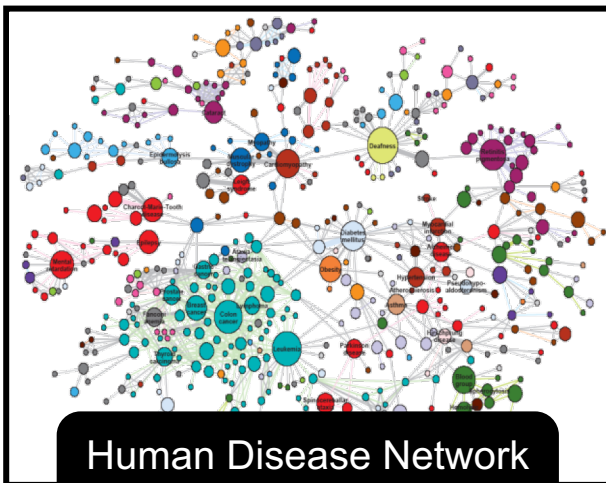
Power grid



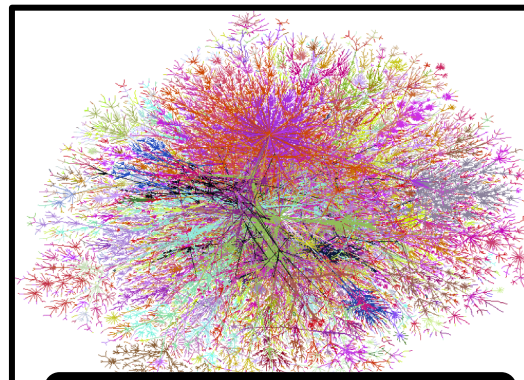
Food Web [2007]



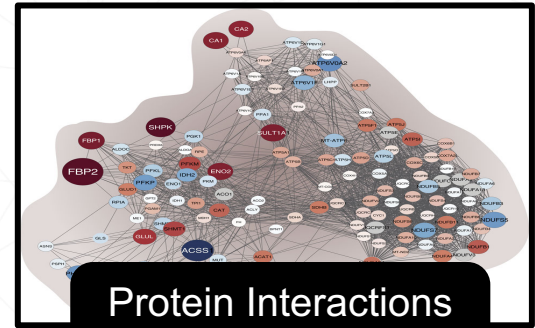
Political blogs



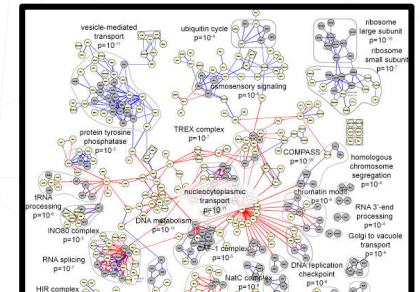
Human Disease Network
[Barabasi 2007]



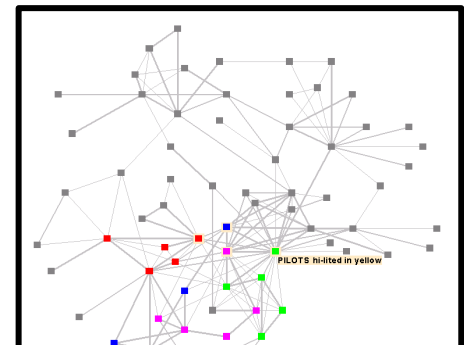
Internet (AS) [2005]



Protein Interactions
[breast cancer]



Gene Regulatory Network
[Decourty 2008]



Terrorist Network
[Krebs 2002]

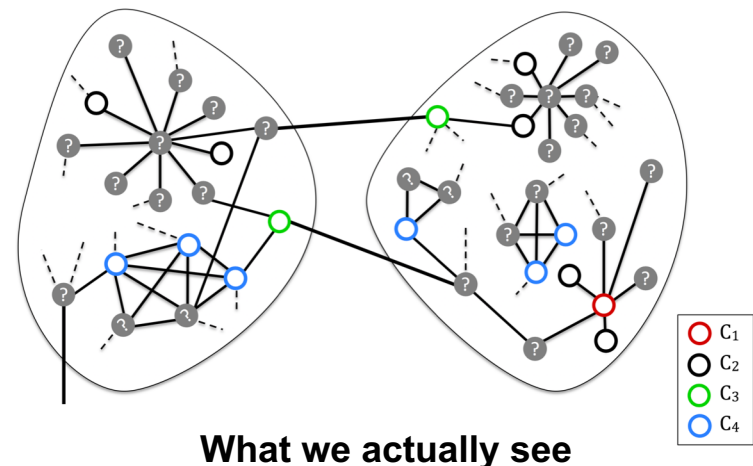
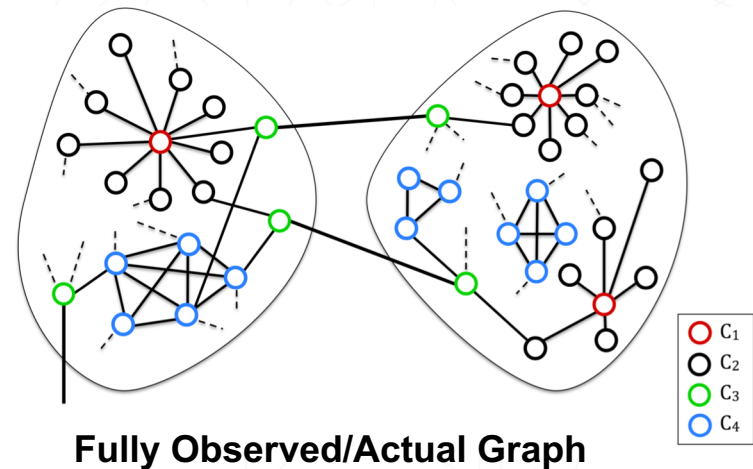
Problem & Motivation

- **Problem:** Given a graph with only a few labeled nodes, the goal is to predict the class labels of the unlabeled nodes
- **Issue:** Existing work assumes “smoothness” of labels over the graph/strong homophily (“birds of a feather flock together”)
 - Works well when the neighboring labels of a node are **highly correlated** (i.e., the neighbors of a node have the same class label), and perform poorly otherwise
- Reverse is often true in actual data

Heterophily Example

Class labels may not be correlated with neighbors (e.g., protein & molecular graphs).

- RSM generalizes across the spectrum of relational data characteristics, and avoids the issues, assumptions, and limitations of existing methods.
- Class of a node may be correlated with nodes that have "similar" structural properties and more generally features (e.g., non-relational attributes, ...).
- Existing methods based on diffusion/label propagation would fail (perform poorly)



This work

- Addresses limitation of previous work that assumes strong homophily between neighboring labels of a node
- Proposed general framework for graphs with arbitrary relational autocorrelation (**homophily** or **heterophily**)

Other Contributions:

- *Principled similarity-based relational learning framework based on the notion of maximizing similarity.*
- Fast, parallel, space-efficient, and flexible with many interchangeable components
- Designed for large-scale supervised *and* semi-supervised learning in noisy multi-dimensional networks

Non-relational example (RSM-IID)

The similarity of the labeled nodes in \mathbf{X} of class k with respect to the test node feature vector \mathbf{z}_i is formalized as,

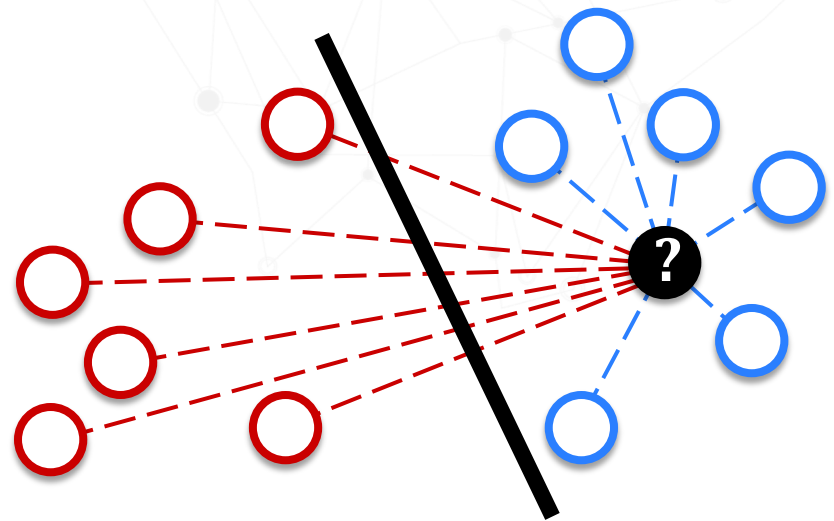
$$w_k = \sum_{\mathbf{x}_j \in \mathcal{X}_k} \Phi \langle \mathbf{z}_i, \mathbf{x}_j \rangle$$

$$\Phi(\mathbf{z}_i, \mathbf{x}_j) = \exp\left(-\frac{\|\mathbf{z}_i - \mathbf{x}_j\|^2}{2\sigma^2}\right)$$

Repeated for each class k to obtain \mathbf{w}

After computing \mathbf{w} , then \mathbf{z}_i is assigned to the class with maximum similarity

$$\xi(\mathbf{z}_i) = \arg \max_{k \in \mathcal{C}} w_k$$



Non-relational example (RSM-IID)

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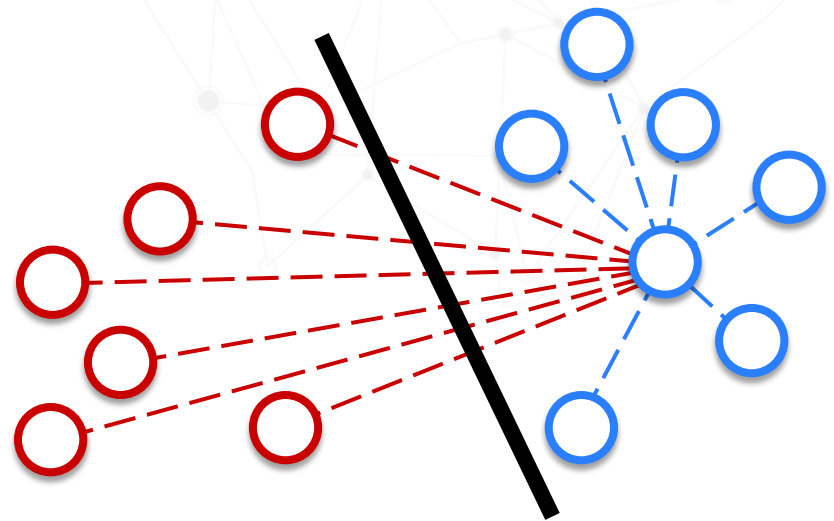
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Supervised & Semi-Supervised Learning Components

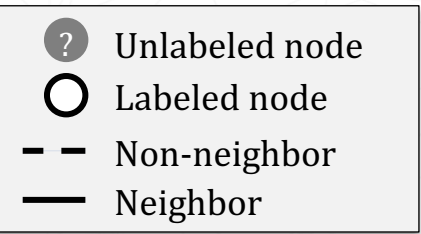
- Supervised component:
 1. Use the nodes with known class labels to predict the class labels of the unknown nodes

- Semi-supervised components:
 1. Iteratively estimate the nodes with unknown class labels, and at each iteration we label a fixed percent of nodes with highest confidence
 2. Sample a small number of unlabeled nodes NOT connected to the node currently being estimated, and weight the similarity by the current class probabilities

Intuition

V^ℓ = nodes with **known labels**

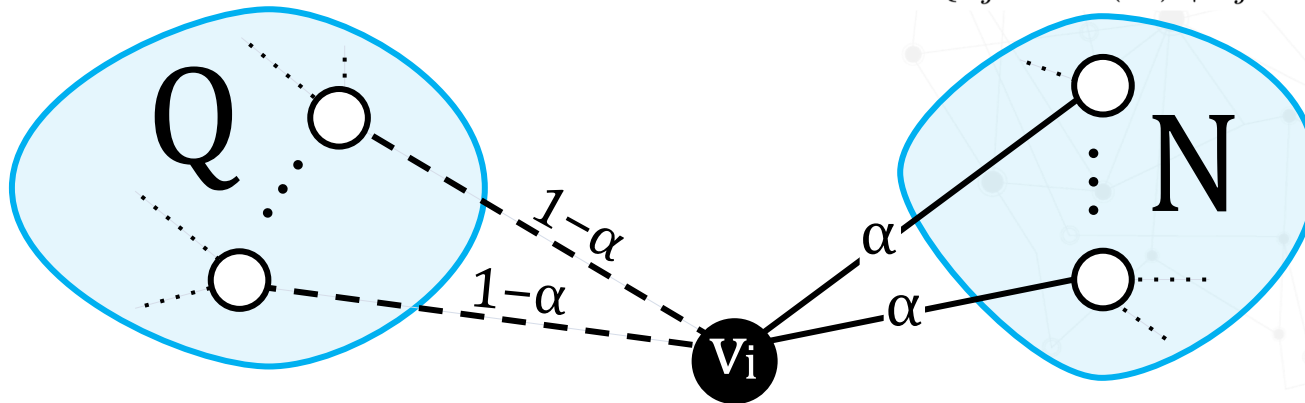
V^u = nodes with **unknown labels**



N and Q = **labeled** neighbors and non-neighbors

$$Q = \{v_j \notin \Gamma_h(v_i) \mid v_j \in V^\ell\}$$

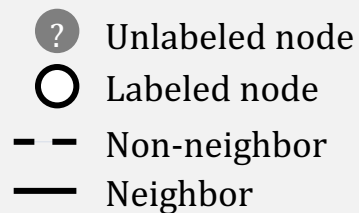
$$N = \{v_j \in \Gamma_h(v_i) \mid v_j \in V^\ell\}$$



Intuition

V^ℓ = nodes with **known labels**

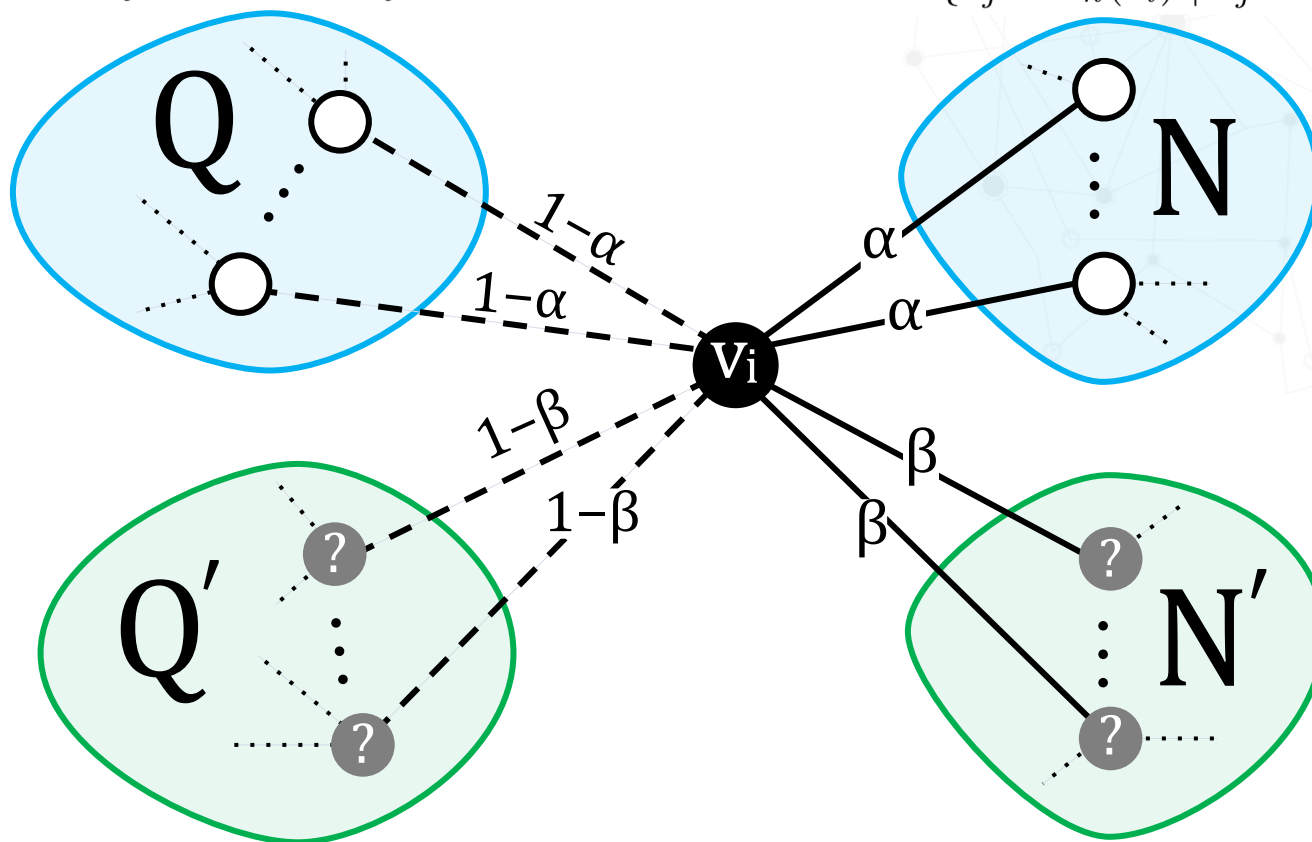
V^u = nodes with **unknown labels**



N and Q = **labeled** neighbors *and* non-neighbors

$$Q = \{v_j \notin \Gamma_h(v_i) \mid v_j \in V^\ell\}$$

$$N = \{v_j \in \Gamma_h(v_i) \mid v_j \in V^\ell\}$$



$$Q' = \{v_j \notin \Gamma_h(v_i) \mid v_j \in V^u\}$$

$$N' = \{v_j \in \Gamma_h(v_i) \mid v_j \in V^u\}$$

N' and Q' = **unlabeled** neighbors *and* non-neighbors

Leveraging Nodes with **Known Labels**

The similarity of the **labeled** nodes in **X** of class k with respect to the test node feature vector \mathbf{z}_i is:

$$w_{ik}^R = \sum_{\mathbf{x}_j \in \mathcal{X}_k \wedge v_j \in N} p_{ik} \Phi\langle \mathbf{z}_i, \mathbf{x}_j \rangle$$

$$w_{ik}^I = \sum_{\mathbf{x}_j \in \mathcal{X}_k \wedge v_j \in Q} p_{ik} \Phi\langle \mathbf{z}_i, \mathbf{x}_j \rangle$$

Repeated for each class k

Obtain a set J by sampling $(V^\ell \cup U)$ via an arbitrary (weighted/uniform) distribution F (if needed, otherwise $J = V^\ell \cup U$)

parallel for each $v_j \in J$ ▷ Supervised component

Set s_{ij} to be $\Phi\langle \mathbf{z}_i, \mathbf{x}_j \rangle$

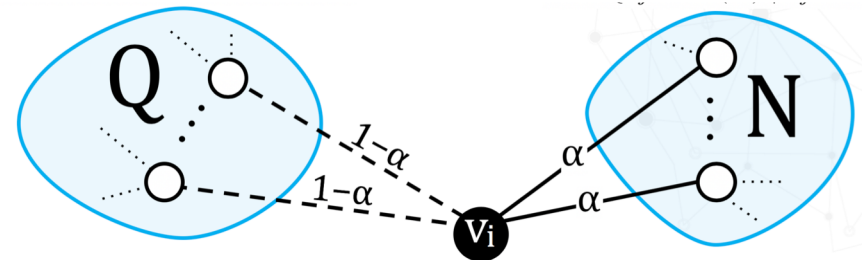
Let $k \in \{1, \dots, |\mathcal{C}|\}$ be the class label of $v_j \in V^\ell$

if $v_j \in \Gamma_h(v_i)$ **then**

Update $w_{ik}^R \leftarrow w_{ik}^R + p_{ik} \cdot s_{ij}$ ▷ labeled *neighbor*

else Update $w_{ik}^I \leftarrow w_{ik}^I + p_{ik} \cdot s_{ij}$ ▷ labeled *non-neigh.*

end parallel



Leveraging Nodes with **Unknown** Labels

- How to make use of unlabeled nodes?

The similarity of the **unlabeled** nodes in \mathbf{Z} with respect to the test node feature vector \mathbf{z}_i is:

$$\mathbf{m}_i^R = \sum_{v_j \in N'} (\mathbf{p}_i \odot \mathbf{p}_j) \cdot \Phi\langle \mathbf{z}_i, \mathbf{z}_j \rangle$$

$$\mathbf{m}_i^I = \sum_{v_j \in Q'} (\mathbf{p}_i \odot \mathbf{p}_j) \cdot \Phi\langle \mathbf{z}_i, \mathbf{z}_j \rangle$$

Obtain a set J by sampling $(V^u \setminus U)$ via an arbitrary (weighted/uniform) distribution F (if needed, otherwise $J = V^u \setminus U$)

parallel for each $v_j \in J$ ▷ Semi-supervised component

Set s_{ij} to be $\Phi\langle \mathbf{z}_i, \mathbf{z}_j \rangle$

for each class $k \in \mathcal{C}$ **do**

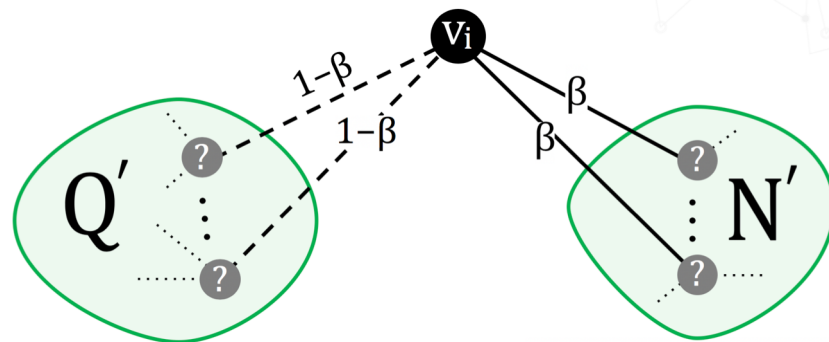
if $v_j \in \Gamma_h(v_i)$ **then**

$m_{ik}^R \leftarrow m_{ik}^R + s_{ij}(p_{ik}p_{jk})$ ▷ unlabeled neighbor

else $m_{ik}^I \leftarrow m_{ik}^I + s_{ij}(p_{ik}p_{jk})$ ▷ unlabel. non-neigh.

end parallel

Weight similarity by the probability that node i and j belong to the same class k



Maximizing Relational Similarity

$$\mathbf{w}_i = \overbrace{\alpha \underbrace{\mathbf{w}_i^R}_{\text{Relational}} + (1 - \alpha) \underbrace{\mathbf{w}_i^I}_{\text{IID}}}_{\text{Supervised}}$$

$$\mathbf{m}_i = \overbrace{\beta \underbrace{\mathbf{m}_i^R}_{\text{Relational}} + (1 - \beta) \underbrace{\mathbf{m}_i^I}_{\text{IID}}}_{\text{Semi-Supervised}}$$

$$\mathbf{p}_i^{(\tau+1)} = \left(\underbrace{\mathbf{w}_i}_{\text{Supervised}} + \underbrace{\mathbf{m}_i}_{\text{SSL}} \right) + \underbrace{\mathbf{p}_i^{(\tau)}}_{\text{previous}}$$

After computing \mathbf{p}_i , then \mathbf{z}_i is assigned to the class with maximum similarity.

$$\xi(\mathbf{z}_i) = \arg \max_{k \in \mathcal{C}} P_{ik}$$

Similarity Functions

- Radial Basis Function (RBF):

$$\Phi(\mathbf{z}_i, \mathbf{x}_j) = \exp\left(-\frac{\|\mathbf{z}_i - \mathbf{x}_j\|^2}{2\sigma^2}\right)$$

- Polynomial functions:

$$\Phi(\mathbf{z}_i, \mathbf{x}_j) = \left(\langle \mathbf{z}_i, \mathbf{x}_j \rangle + c\right)^q$$

- Sigmoid kernel:

$$\Phi(\mathbf{z}_i, \mathbf{x}_j) = \tanh(a \langle \mathbf{z}_i, \mathbf{x}_j \rangle + c)$$

...among many other possibilities...

Complexity Analysis

n = # of nodes
 d = # of features
 k = # of class labels

■ Computational Complexity:

Reduced by sampling from the different types of nodes

- Single test instance: $\mathcal{O}(|J| \cdot d)$ where $|J| \ll n$

■ Space Complexity:

- Given a test node to predict, RSM takes $\mathcal{O}(k)$ space
- If collective inference is used, then RSM takes $\mathcal{O}(nk)$

In addition to graph and features

An abstract network diagram in the top right corner, featuring a central node connected to many other nodes, forming a complex web of lines and dots.

Experiments

Experimental setup

- Model selected via grid search

$$\alpha, \beta \in \{0, 0.01, 0.1, 0.25, 0.5, 0.75, 0.99, 1\}$$

$$\sigma \in \{0.001, 0.01, 0.05, 0.1\}$$

- 10% of the labeled nodes as training
- Results are averaged over 20 trials
- Attributes = degree, 3- and 4-node graphlets

Heterophily Experiments

- RSM outperforms WVRN, SVM-G, and RPT across all graphs with a mean gain of **24%, 52%, and 17%**, respectively
- RSM is effective for graphs with heterophily

HETEROPHILY CLASSIFICATION RESULTS

Graph	$ \mathcal{C} $	\mathbb{L}	F1 score				
			RSM	RSM-IID	WVRN	SVM-G	RPT
DD645	20	2.0%	0.769	0.701	0.607	0.634	0.680
DD411	20	12.5%	0.712	0.695	0.605	0.239	0.615
DD5	19	6.7%	0.561	0.510	0.303	0.426	0.465
DD244	20	7.1%	0.742	0.708	0.558	0.175	0.646
DD159	20	2.70%	0.734	0.702	0.605	0.280	0.652
DD185	18	12.5%	0.738	0.644	0.585	0.262	0.489

homophily measure $\mathbb{L}(G) = 1/|E| \sum_{(v_i, v_j) \in E} \mathbb{L}(v_i, v_j)$
 $\mathbb{L}(v_i, v_j) = 1$ if class labels of v_i and v_j match, otherwise 0

Homophily Experiments

- RSM significantly outperforms the other methods
- Effective for classification on graphs with homophily
- Flexible for prediction in graphs with arbitrary relational autocorrelation (homophily or heterophily)

CLASSIFICATION RESULTS FOR GRAPHS WITH HOMOPHILY

Graph	$ \mathcal{C} $	\mathbb{L}	Accuracy				
			RSM	RSM-IID	WVRN	SVM-G	RPT
aff-polbooks	3	66.6%	89.25	71.16	74.41	69.89	70.97
bio-Gene	2	79.7%	85.27	64.88	72.41	61.85	60.24
Enzymes349	2	50.0%	77.81	67.93	62.50	55.36	66.07
musicGenre	8	84.9%	82.35	51.57	60.59	48.63	55.56

homophily measure

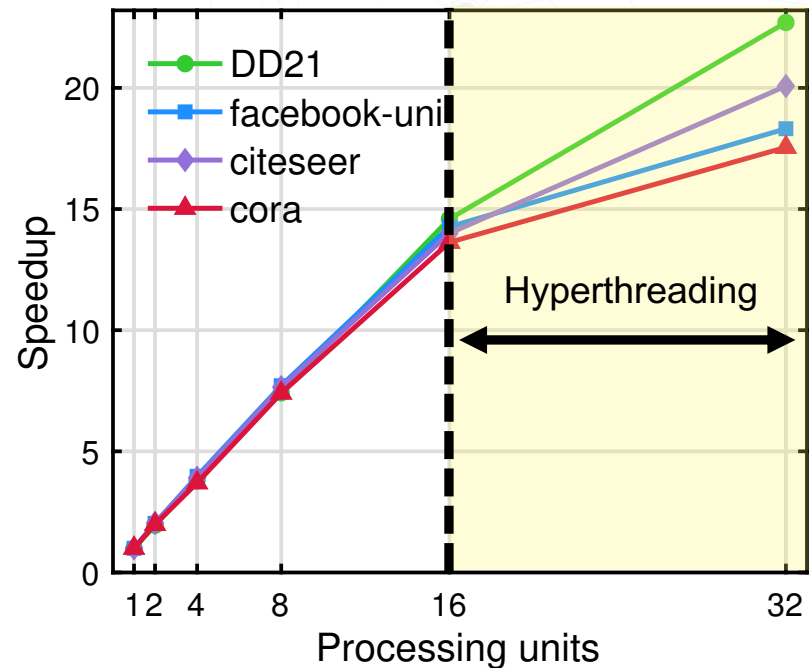
$$\mathbb{L}(G) = 1/|E| \sum_{(v_i, v_j) \in E} \mathbb{L}(v_i, v_j)$$

$$\mathbb{L}(v_i, v_j) = 1 \text{ if class labels of } v_i \text{ and } v_j \text{ match, otherwise } 0$$

Parallel Scaling

$$S_p = \frac{T_{\text{seq}}}{T_p}$$

- Strong scaling results
- RSM scales nearly linearly as the number of processors increases



Note a machine with two Intel Xeon E5-2687 CPUs @3.10GHz were used with 8 cores each.

Runtime Performance

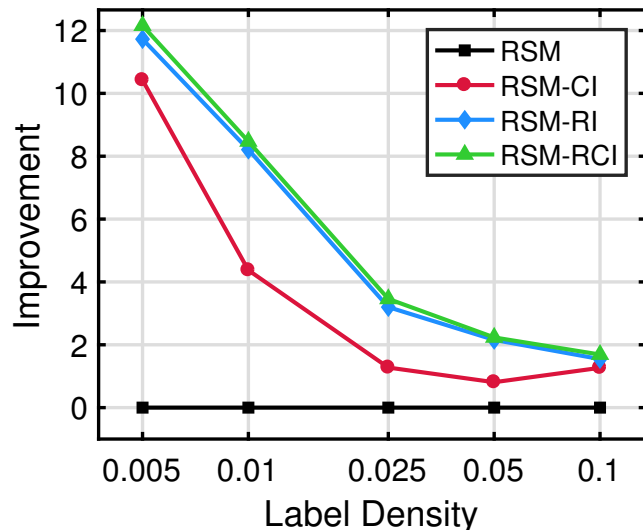
- RSM is fast with real-time response times
 - in the range of a few ms or less
- Able to support real-time interactive learning & inference

AVERAGE TIME PER TEST INSTANCE

Graph	$ V^\ell $	$ \mathcal{C} $	avg. time
soc-TerroristRel	90	2	0.18 ms
aff-polbooks	12	3	0.12 ms
cora	272	7	0.97 ms
DD6	417	20	3.10 ms
political-retweet	1848	2	0.15 ms

Varying RSM Inference Types

1. **Collective Inference (CI):** Uses neighbor labels
2. **Relational Inference (RI):** Uses neighbor attributes
3. **Relational-Collective Inference (RCI):** Uses both neighbor labels and neighbor attributes

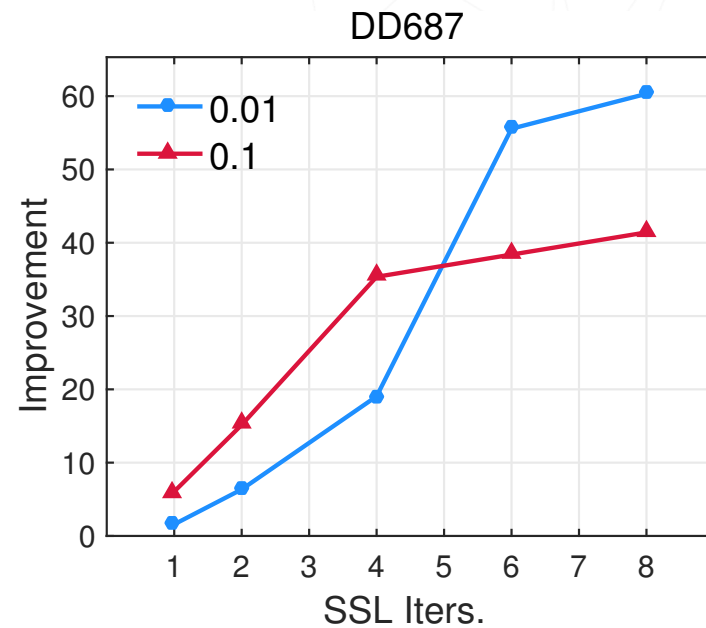
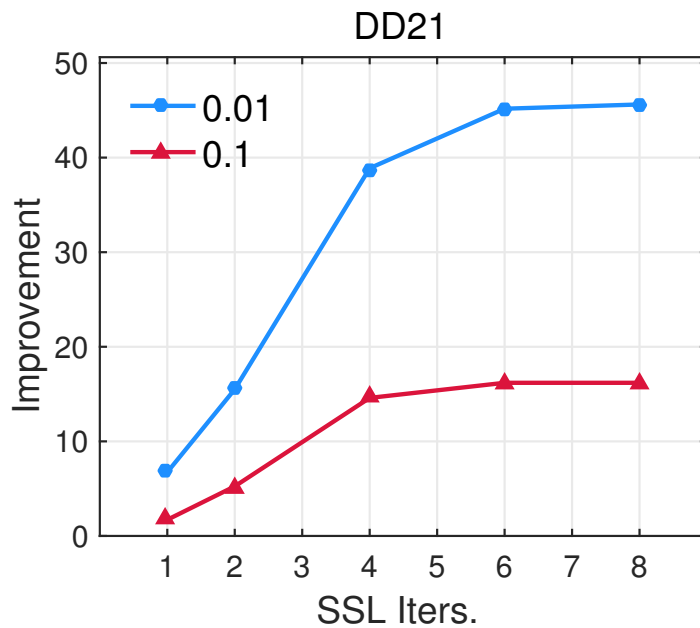


Impact of different classes of features/inference on classification (soc-TerrorRel.)

Accuracy (percent) improvement of RSM-CI, RSM-RI, and RSM-RCI over a basic variant of RSM.

Varying SSL iterations & known labels

- Improvement over label propagation as the # of SSL iterations increases
- More iterations appears to perform better when very few known labels

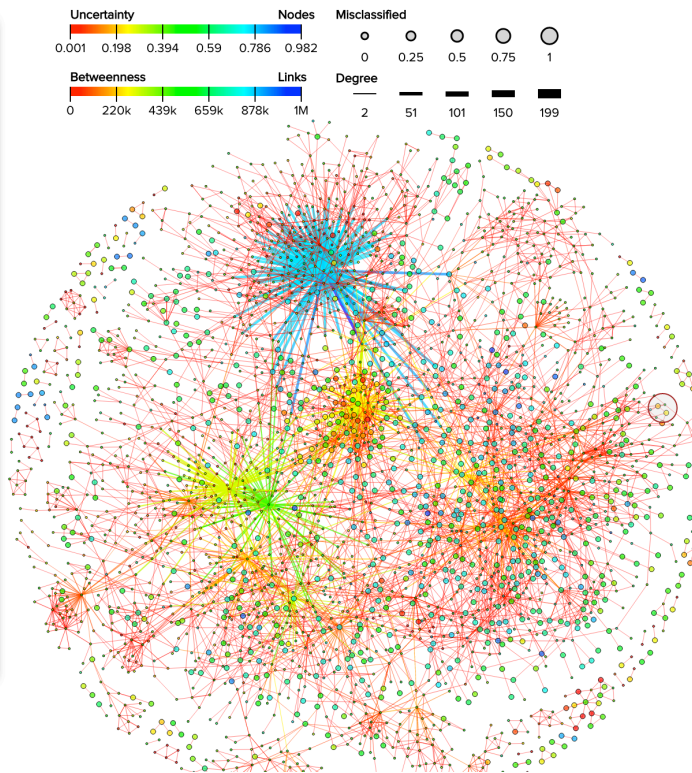


Effectiveness for Interactive RML

Methods often fail in practice due to low relational autocorrelation, noisy links, sparsely labeled graphs, and data representation

Class of RSM models are designed to be fast for interactive RML

cora		
V	2708	840
E	5429	881
density	0.001	0.003
max degree	169	42
avg degree	4.01	2.10
T	5496	577
avg triangles	2.0	0.7
max triangles	170	22
local clustering	0.24	0.16
global clustering	0.10	0.14
assortativity	-0.0656	-0.0658
max k-core	5	3
max triangle-core	4	0
chromatic num.	7	5
max indep. set	1244	505
num communities	362	140
num roles	8	6
max betweenness	0.9M	32K
diameter	19	19
mean distance	5.87	3.79
max pagerank	0.0121	0.0142
wedges	49K	3.5K
4-clique	245	16
4-chordal-cycle	2.7K	184
4-tailed-tri	57K	90
4-cycle	1.6K	9K
3-star	1.1M	18K
4-path	0.2M	2.2K
4-triangle	4.6M	0.3B
4-2star	0.1B	0.4M
4-2edge	14M	2.9M
4-fedge	20B	0.1M
4-indep.	2.2T	20B
label density	0.80	1
num classes	7	7
accuracy	85.01%	55.48



INTERACTIVE RELATIONAL LEARNING

Class label

Class label

Local model

Class dist.

Variant

Collective RSM

Similarity

RBF

σ sigma

0.1

α alpha

0.5

β beta

0.5

Max iter.

5

Trials

1

K-fold

5

Label density

1

CC Label Perc.

0.2

Feat. Norm.

Min-max Norm.

Node Norm.

L1 Norm.

Norm similarity

☒

Add Prior

☒

Meta-features

☒

SSL-Sim

☐

BP Prior Est.

☒

Evaluate Models

☐

Select Model Attrs.

☐

Learn Model

☐

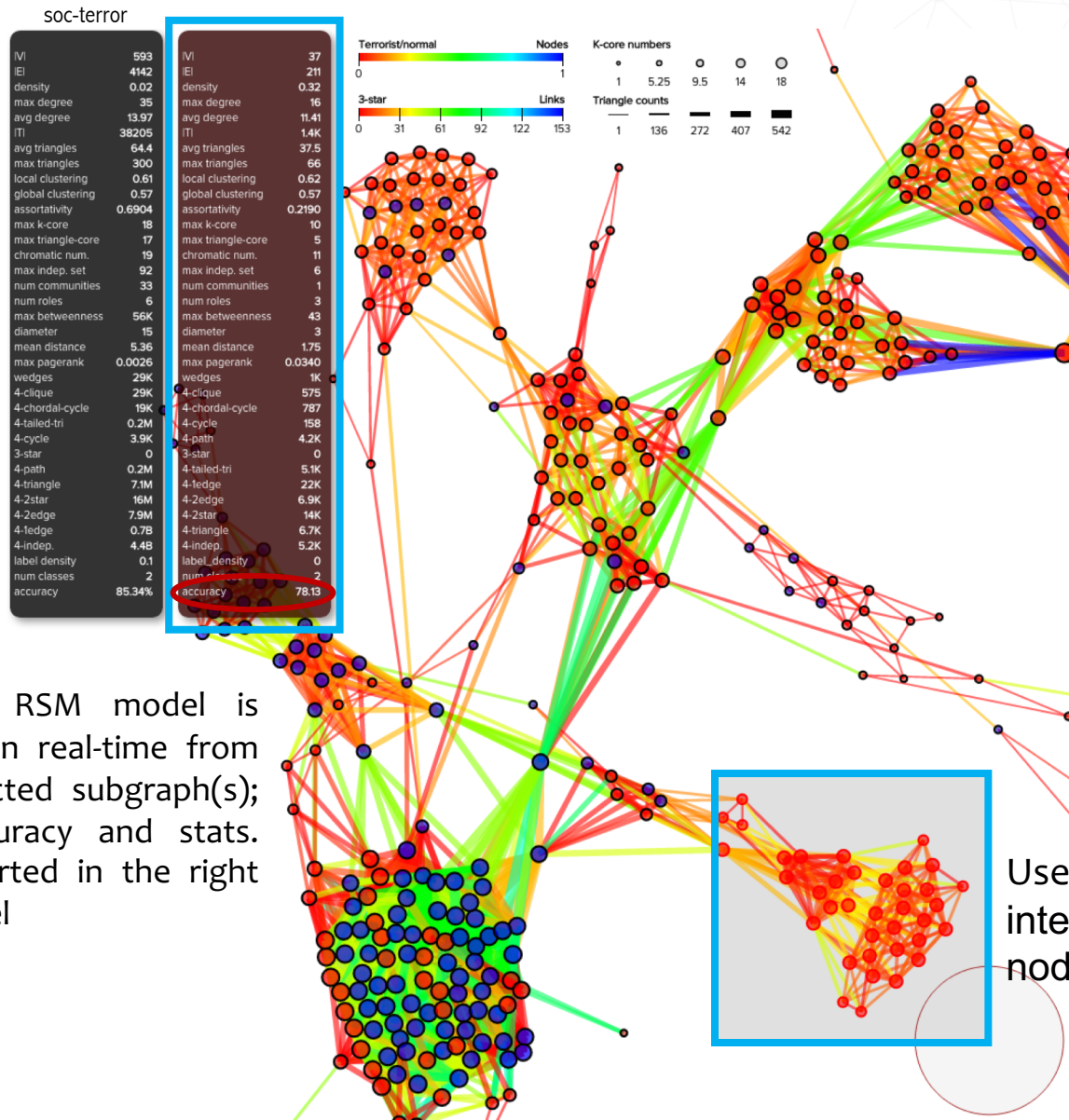
GRAPH GENERATION PARAMETERS

Close Controls

Users can **specify** the **RSM model** in real-time using a visual interface as well as perform evaluation, analyze errors, and make adjustments and refinements in a closed-loop.

Users can search the space of RSM models in an interactive and visual fashion in real-time

Effectiveness for Interactive RML



A local RSM model is learned in real-time from the selected subgraph(s); and accuracy and stats. are reported in the right side panel

Users can **select** subgraph(s) of interest by visually selecting nodes and edges.

Summary and Conclusion

- Introduced a general principled similarity-based relational learning framework
- Accurate for graphs with **arbitrary relational autocorrelation** (homophily *and* heterophily)
 - Previous methods perform well only when there is strong homophily
- Fast and scalable
 - Supports large-scale graphs, and applications requiring real-time performance such as interactive relational learning
- Flexible with many interchangeable components

Thanks!

Questions?



Data accessible online:

<http://networkrepository.com>

